

## Deriving Equations

- ◆  $P_i(t + \Delta t)$  = probability of being in state  $S_i$  after  $\Delta t$

$$P_i(t + \Delta t) = P_i(t)[1 - \sum_{i \neq j} \lambda_{ij} \Delta t] + \sum_{i \neq j} P_j(t) \lambda_{ji} \Delta t$$

as  $\Delta t \rightarrow 0$

(differentiate)

$$\lim_{\Delta t \rightarrow 0} \frac{P_i(t + \Delta t) - P_i(t)}{\Delta t} = -P_i(t) \sum_{i \neq j} \lambda_{ij} + \sum_{i \neq j} P_j(t) \lambda_{ji}$$

## Deriving Equations

- ◆ With  $m$  states  $\Rightarrow m$  differential equations
- ◆  $m-1$  independent equations

$$\frac{dP_1(t)}{dt} = \sum_{j \neq 1} P_j(t) \lambda_{j1} - P_1(t) \sum_{j \neq 1} \lambda_{1j}$$

$$\frac{dP_i(t)}{dt} = \sum_{j \neq i} P_j(t) \lambda_{ji} - P_i(t) \sum_{j \neq i} \lambda_{ij}$$

$$\frac{dP_{m-1}(t)}{dt} = \sum_{j \neq m-1} P_j(t) \lambda_{j(m-1)} - P_{m-1}(t) \sum_{j \neq m-1} \lambda_{(m-1)j}$$

- ◆  $m^{\text{th}}$  equation

$$1 = \sum_{\forall k} P_k(t)$$

## Deriving Equations

### ◆ Matrix Notation

$$\begin{bmatrix} \frac{dP_1(t)}{dt} \\ \frac{dP_i(t)}{dt} \\ \frac{dP_{m-1}(t)}{dt} \\ 1 \end{bmatrix} = \begin{bmatrix} -\sum_{j \neq 1} \lambda_{1j} & \lambda_{21} & \lambda_{31} & \dots & \lambda_{m1} \\ \lambda_{1i} & \lambda_{2i} & \dots & -\sum_{j \neq i} \lambda_{ij} & \lambda_{mi} \\ \lambda_{1(m-1)} & \dots & & -\sum_{j \neq m-1} \lambda_{(m-1)j} & \lambda_{m(m-1)} \\ 1 & 1 & \dots & 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} P_1 \\ P_i \\ P_{m-1} \\ P_m \end{bmatrix}$$

## Steady State Solutions

### ◆ Steady state solution:

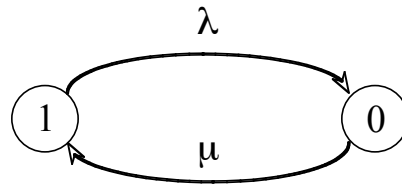
$$\lim_{t \rightarrow \infty} \frac{dP_j(t)}{dt} = 0$$

### ◆ Steady state solution = Availability

- set of linear alg. equations rather than linear differential equations

## Steady State Solution

- ◆ Example: Simplex system with repair



$\lambda$  = failure rate

$\mu$  = repair rate

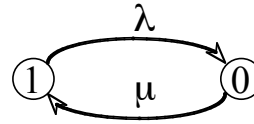
$$\begin{bmatrix} \frac{dP_0}{dt} \\ 1 \end{bmatrix} = \begin{bmatrix} -\mu & \lambda \\ 1 & 1 \end{bmatrix} \begin{bmatrix} P_0 \\ P_1 \end{bmatrix}$$

$$b = Ax$$

$$\begin{bmatrix} \frac{dP_0}{dt} \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -\mu & \lambda \\ 1 & 1 \end{bmatrix} \begin{bmatrix} P_0 \\ P_1 \end{bmatrix}$$

## Steady State Solution

- ◆ Simplex with Repair
- ◆ Solution:



$$P_0 = \frac{\lambda}{\mu + \lambda} \quad P_1 = \frac{\mu}{\mu + \lambda}$$

- ◆ Steady State Availability

$$P_1 = \frac{\mu}{\mu + \lambda} = \lim_{t \rightarrow \infty} A(t)$$

- ◆ e.g.

$$\begin{aligned} \lambda = 10^{-3} &\Rightarrow MTTF = 1000h \\ \mu = 10^{-1} &\Rightarrow MTTR = 10h \end{aligned}$$

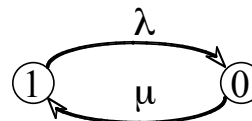
Availability:

The prob. that  
system is up

$$\begin{aligned} A &= \frac{10^{-1}}{10^{-1} + 10^{-3}} \\ &= 0.99 = 99\% \end{aligned}$$

## Transient Solution

- ◆ Simplex with Repair



$$\frac{dP_1(t)}{dt} = \mu P_0(t) - \lambda P_1(t)$$

with  $P_0(t) + P_1(t) = 1$  we get

$$\begin{aligned} \frac{dP_1(t)}{dt} &= \mu(1 - P_1(t)) - \lambda P_1(t) \\ &= -P_1(t)(\mu + \lambda) + \mu \end{aligned}$$

- ◆  $P_1'(t) + (\mu + \lambda)P_1(t) = \mu$  is a first order diff. equation

## Transient Solution

- ◆  $P_1'(t) + (\mu + \lambda)P_1(t) = \mu$  has general solution

$$P_1(t) = \frac{\mu}{\mu + \lambda} + Ce^{-(\mu + \lambda)t}$$

- ◆ Get  $C$  by setting  $t=0$

$$C = P_1(0) - \frac{\mu}{\mu + \lambda}$$

- ◆ Solution

$$P_1(t) = \frac{\mu}{\mu + \lambda} + \left( P_1(0) - \frac{\mu}{\mu + \lambda} \right) e^{-(\mu + \lambda)t}$$

## Transient Solution

- ◆ with  $t \rightarrow \infty$  we get

$$P_1(t) = \frac{\mu}{\mu + \lambda} + \left( P_1(0) - \frac{\mu}{\mu + \lambda} \right) e^{-(\mu + \lambda)t}$$

$$= \frac{\mu}{\mu + \lambda} \quad \leftarrow \text{our steady state solution (steady state availability)}$$

